## Problem 1. K-means and Gaussian Mixture Model

The Gaussian mixture model can be written as the superposition of Gaussians in the form

$$p(\mathbf{x}_i) = \sum_{k=1}^{K} p_k \phi(\mathbf{x}_i \mid \mu_k, \boldsymbol{\Sigma}_k),$$

where  $\phi$  is the normal density with mean  $\mu_k$  and covariance matrix  $\Sigma_k$ , and  $p_k$  the probability that the *i*-th observation  $\mathbf{x}_i$  belongs to class k.

(*i*) Derive the EM algorithm for the Gaussian mixture model.

The K-means algorithm partitions the dataset into K clusters, where K is supposed fixed in advance. For each datapoint  $\mathbf{x}_i$ , we assign a binary variable  $\pi_{ik}$  describing which cluster the variable belongs to,

$$\pi_{ik} = \begin{cases} 1 & \text{if } \mathbf{x}_i \text{ belongs to cluster } k \\ 0 & \text{otherwise.} \end{cases}$$

The goal is to select  $\pi := \{\pi_{ik}\}$  and K centers  $z_k$  such that

$$C(z_1, \dots, z_K, \pi) = \sum_{k=1}^K \sum_{i=1}^n |\pi_{ik}| |\mathbf{x}_i - z_k||^2$$

is minimized.

(ii) Show that this can be achieved using a two-step iterative procedure, where

Step (a) Assign  $\mathbf{x}_i$  to the nearest  $\mu_k$ 

Step (b) Update  $\mu_k$  using

$$\mu_k = \frac{\sum_i \pi_{ik} \mathbf{x}_i}{\sum_i \pi_{ik}}$$

(iii) Consider a Gaussian mixture model with covariance matrices given by  $\epsilon \mathbf{I}$ , where  $\epsilon$  is a variance parameter shared by all components. Show that in the limit  $\epsilon \rightarrow 0$ , the EM re-estimation for the Gaussian means  $\mu_k$  reduces to the K-mean result. Then show that in this limit, maximising the expected complete log-likelihood is equivalent to minimising  $C(z_1, \ldots, z_K, \pi)$ .

## **Problem 2.** EM algorithm for binomial count data

Consider a set of n observations  $\mathcal{L}_n = \{x_1, \ldots, x_n\}$ , where each  $x_i \in \{0, 1, 2, \ldots\}$ . Assume that observation  $x_i$  belongs to category k with probability  $\pi_k$ , with  $k = 1, \ldots, K$ , and that given  $x_i$  belongs to category k,

$$x_i \sim Bi(n_i, p_k)$$
.

We do not know the category label of each observation, but we assume that the  $n_i$  are known. Write down the EM algorithm estimating the parameters  $\pi_1, \ldots, \pi_K, p_1, \ldots, p_K$ .

## Problem 3. EM algorithm for censored data

Suppose that  $x_1, \ldots, x_n$  are independent truncated observations of a normally distributed random variable. Specifically, each  $x_i$  is a realisation of a generic X, where

$$X = \min(X^*, a)$$
, and  $X^* \sim \mathcal{N}(\theta, 1)$ .

We suppose a > 0 known, and we wish to estimate  $\theta$  based solely on observations  $x_1, \ldots, x_n$ . We denote by  $x_1^*, \ldots, x_n^*$  the associated partially observed variables.

(i) To simplify notation, denote the first  $m \leq n$  observations  $x_1 = x_1^*, \ldots, x_m = x_m^*$  as uncensored, and the remaining (n - m) as censored. The censored observations are treated as latent variables. We denote them by  $z_{m+1} = x_{m+1}^*, \ldots, z_n = x_n^*$  (instead of  $z_{m+1}, \ldots, z_n$ , you observe n - m times the value a, as  $x_{m+1} = \ldots = x_n = a$ ). Ignoring constants independent of  $\theta$ , show that the complete log-likelihood can be written

$$\ell(\theta|x_1,\ldots,x_m,z_{m+1},\ldots,z_n) = -\frac{1}{2}\sum_{i=1}^m (x_i-\theta)^2 - \frac{1}{2}\sum_{i=m+1}^n (z_i-\theta)^2.$$

(ii) Deduce from (i) the expression of the likelihood,

$$f(\theta|x_1...,x_n) = \frac{1}{(2\pi)^{m/2}} \exp\left\{-\frac{1}{2}\sum_{i=1}^m (x_i-\theta)^2\right\} (1-\Phi(a-\theta))^{n-m}$$

(iii) Show that the latent variables  $z_i$ , for i = m + 1, ..., n, have conditional density

$$k(z_i|X_i = a, \theta) = \frac{\varphi(z_i - \theta)}{1 - \Phi(a - \theta)}, \quad a \le z_i,$$

and zero elsewhere, where  $\varphi$  and  $\Phi$  denote the standard normal density and distribution, respectively.

(iv) We compute the E-step of the EM algorithm. Show that

$$\mathbf{E}(Z|\theta^{(m)}) = \theta^{(m)} + \frac{\varphi(a-\theta^{(m)})}{1-\Phi(a-\theta^{(m)})},$$

and write down the expression of  $Q(\theta, \theta^{(m)})$ .

(v) Show that the M-step returns the following update

$$\theta^{(m+1)} = \frac{m}{n}\bar{x} + \frac{n-m}{n}\left(\theta^{(m)} + \frac{\varphi(a-\theta^{(m)})}{1-\Phi(a-\theta^{(m)})}\right),$$

where  $\bar{x} = m^{-1} \sum_{i=1}^{m} x_i$ .